GDELPHI SERIES



Delphi ND Series Non-Isolated Point of Load DC/DC Modules: 8.0V~13.8Vin, 0.9V~5.0Vout, 40A

The Delphi ND40 Series, 8.0V~13.8V input, single output, non-isolated point of load DC/DC converters are the latest offering from a world leader in power systems technology and manufacturing - Delta Electronics, Inc. The ND40 series provides up to 40A of power in a vertical mounted through-hole package and the output can be resistor-trimmed from 0.9Vdc to 5.0Vdc. ND40 provides a very cost effective point of load solution. With creative design technology and optimization of component placement, these converters possess outstanding electrical and thermal performance, as well as extremely high reliability under highly stressful operating conditions.

FEATURES

- High efficiency:
 94% @ 12Vin, 5V/40A out
- Size:
- 36.8mm x 32.2mm x 13.0mm (Vertical) (1.45"x1.27"x0.51") 36.8mm x 32.2mm x 14.8mm (Horizontal) (1.45"x1.27"x0.58")
- Resistor-based trim
- No minimum load required
- Output voltage programmable from 0.9-5.0V via external resistors
- Fixed frequency operation
- Input UVLO, output OVP (non-latch) and OCP (non-latch)
- Remote ON/OFF (default: positive)
- Remote sense
- Power good function
- ISO 9001, TL 9000, ISO 14001, QS9000, OHSAS18001 certified manufacturing facility
- UL/cUL 60950-1 (US & Canada) Recognized,

APPLICATIONS

- DataCom
- Distributed power architectures
- Servers and workstations
- LAN / WAN applications
- Data processing applications





TECHNICAL SPECIFICATIONS

(Ambient Temperature=25°C, minimum airflow=300LFM, nominal V_{in}=12Vdc unless otherwise specified.)

PARAMETER	NOTES and CONDITIONS	ND12S0A0V40 (standard)				
		Min.	Тур.	Max.	Units	
ABSOLUTE MAXIMUM RATINGS						
Input Voltage (Continuous)	Befor to Figure 20 for the manufing point	0		13.8	Vdc °C	
Storage Temperature	Refer to Figure 30 for the measuring point	-40		125	0°C	
INPUT CHARACTERISTICS						
Operating Input Voltage		8.0	12	13.8	Vdc	
Input Under-Voltage Lockout	10= 50% of 10,max		7.8		Vdc	
Turn-Off Voltage Threshold			6.2		Vdc	
Lockout Hysteresis Voltage			1.6		Vdc	
Maximum Input Current	Vin= 8V, Vo=5V, 100%Load			40	Adc	
Peak Inrush Current				200	Apk	
Recovery Time	Inrush Decay to Normal			100	mS	
External Input Capacitance	The dielectric of ceramic capacitance shell be X5R or X7R	22		100	μF	
Vo Reak Deviation of Input Step Response	Vin step change of ±1.8V, dv/dt of Vin =0.2V/uS			2 100	A/µS	
OUTPUT CHARACTERISTICS				100	IIIV	
Output Voltage Adjustable Range	Selected by an external resistor	0.9		5.0	Vdc	
Output Voltage Set Point	Io=Io,max ,Rtrim:±0.1% tolerance , Tc=±25ppm	-1		+1	% Vo,set	
Stability, Long Term Voltage Drift	Vin=12V,Io=Io,max, record over 24hours	-0.1		+0.1	% Vo,set	
Over Line	Vin=Vin min to Vin max			0.2	% Vo set	
Over Load	Io=Io,min to Io,max			0.5	% Vo,set	
Over Temperature	Ta=-5℃ to 60℃			0.75	% Vo,set	
Total Output Voltage Range	Over all operation input voltage, resistive load, and	-3.0		+3.0	% Vo,set	
	5Hz to 20MHz bandwidth 10uE tantalum // 1uE ceramic					
Output Voltage Ripple and Noise	Vin=min to max, Io=min to max					
Peak-to-Peak	$0.9 \leq Vo, set < 1.5V$			30	mVp-p	
Peak-to-Peak	1.5≦Vo,set<3.5V			40	mVp-p	
Peak-to-Peak	$3.5 \leq Vo, set \leq 5.0V$	-		85	mVp-p	
Output Current Range		0		40	Adc	
Minimum Output capacitance	ESR≧2mΩ	300			uF	
Maximum Output capacitance	ESR≧0.2mΩ			2000	μF	
Loop Stability	Cout from 300µF to 2000µF					
Phase Margin			45		Degree	
Output Voltage Over-shoot at Start-up			0	5	% Vo set	
Output Current-Limit Inception	Hiccup mode	110		200	%lo,max	
Output Over Voltage Protection	Hiccup mode	110			% Vo,set	
DYNAMIC CHARACTERISTICS	5Hz to 20MHz bandwidth 10uE tantalum // 1uE caramic					
Dynamic Load Response	dlo/dt=2.5A/Us, Step load Freq.=200Hz~ 2.5KHz					
Positive Step Change in Output Current	50% lo, max to 100% lo, max		150	200	mVpk	
Negative Step Change in Output Current	100% Io, max to 50% Io, max		150	200	mVpk	
Turn-On Transient				100	μs	
Start-up Time, From On/Off Control	From Enable High to 90% of Vo			7	ms	
Start-Up Time, From Input	From Vin to 90% of Vo			7	ms	
	V_{in} 10 V_{in} is max Te 25%	80	90			
V0,Set=0.9V	Vin=12V, Io=Io,max, Ta=25°C	82	02 84		% %	
Vo.set=1.2V	Vin=12V, Io=Io,max, Ta=25°C	83	86		%	
Vo,set=1.8V	Vin=12V, Io=Io,max, Ta=25℃	84	89		%	
Vo,set=2.5V	Vin=12V, Io=Io,max, Ta=25℃	84	90		%	
Vo,set=3.3V	Vin=12V, Io=Io,max, Ta=25°C	86	92		%	
Vo,set=5.0V	Vin=12V, Io=Io,max, Ta=25℃	89	94		%	
FEATURE CHARACTERISTICS	$500kHz$ operation for 2.2V \leq Ve pet \leq 5.0V		500/220		kHa	
ON/OFE Control (Logic High-Module ON)			500/220		КПД	
Logic High Voltage	Module On	2.7			Vdc	
Logic Low Voltage	Module Off			0.44	Vdc	
Logic High Current				125	μΑ	
Power Good				200	μΑ	
PG Delay Time from Vin	Vin=Vin,min, Vo is between 95% - 105% of Vo,set			15	mS	
PG Delay Time from Enable	Enable=H, Vo is between 95% - 105% of Vo,set			15	mS	
Kemote Sense Range		50			m\/	
Vo,max When Remote Sense Line Open		50		105	%Vo.set	
GENERAL SPECIFICATIONS					,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
MTBF	lo=80%lo, max, Ta=25℃		3.6		M hours	
Weight			20.5		grams	

























Figure 6: Converter efficiency vs. output current (3.3V output voltage)







Figure 9: Output ripple & noise at 12 Vin, 1.2 V/40A out



Figure 11: Typical transient response to step load change at 2.5A/μS between 50% and 100% of lo, max at 12Vin, 1.2V out (Cout = 300uF ceramic, 1uF ceramic, 10μF tantalum)

2.501650 2856 C 632 836 2040 2448 2652 204 408 612 816 020 428 2244 224 Minute

Figure 8: Long term voltage drift over 24hr at 2.5V/40A out

2.502100

2.502050

2.502000

2.501950

2.501900

2.501850 2.501800

2.501750

2.501700

Output Voltage (V)



Figure 10: Output ripple & noise at 12 Vin, 5.0 V/40A out



Figure 12: Typical transient response to step load change at 2.5A/ μ S between 50% and 100% of Io, max at 12Vin, 5.0V out (Cout = 300 μ F ceramic, 1 μ F ceramic, 10 μ F tantalum)





Figure 13: Typical transient response to step load change at 2.5A/μS between 50% and 100% of Io, max at 12Vin, 1.2V out (Cout = 2000uF ceramic, 1uF ceramic, 10μF tantalum)



Figure 15: Typical transient response? When the point voltage change at 0.2V/μS between 12Vin and 13.8Vin at 1.2V/0A out (Cout = 300uF ceramic, 1uF ceramic, 10μF tantalum) Ch1: Vin, Ch2: Vo



Figure 17: Turn on delay time at 12vin, 0.9V/40A out Ch1: Vin, Ch2: Vo



Figure 14: Typical transient response to step load change at 2.5A/μS between 50% and 100% of lo, max at 12Vin, 5.0V out (Cout = 2000uF ceramic, 1uF ceramic, 10μF tantalum)



Figure 16: Typical transient response Wester input voltage change at 0.2V/μS between 12Vin and 13.8Vin at 5.0V/0A out (Cout = 300uF ceramic, 1uF ceramic, 10μF tantalum) Ch1: Vin, Ch2: Vo



Figure 18: Turn on delay time at 12vin, 5.0V/40A out Ch1: Vin, Ch2: Vo





Figure 19: Turn on delay time at Remote On/Off, 0.9V/40A out Ch1: Enable pin, Ch2: Vo







Figure 23: Output short circuit current at 12 Vin, 1.2 Vout Ch1: Vo, Ch2: PG, C3: Io



Figure 20: Turn on delay time at Remote On/Off, 5.0V/40A out Ch1: Enable pin, Ch2: Vo







Figure 24: Output short circuit current at 12Vin, 5.0Vout Ch1: Vo, Ch2: PG, C3: Io



DESIGN CONSIDERATIONS

The ND 40A uses two phase and peak current mode controlled buck topology. The output can be trimmed in the range of 0.9Vdc to 5.0Vdc by a resistor between Trim+ pin and Trim- pin.

The module can be turned ON/OFF by remote control with positive on/off logic to ENABLE pin. The converter DC output is disabled when the signal is driven low (below 0.44V).

The module can protect itself by entering hiccup mode against over current, short circuit, over voltage condition.

Safety Considerations

For safety-agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a maximum 40A or two paralleled 20A of fast-acting fuses in the ungrounded lead.

FEATURES DESCRIPTIONS

Enable On/Off

The module can be turned ON/OFF by remote control with positive on/off logic to ENABLE pin.

For positive logic module, the On/Off pin is pulled high with an external pull-up resistor, $R_{pull-up}$, (see figure 25) Positive logic On/Off signal turns the module ON during logic high and turns the module OFF during logic low. If the positive On/Off function is not used, connect ENABLE pin to Vin with $R_{pull-up}$. (The module will be On) $R_{pull-up}$ of 100kohm is recommended.



Fig. 25. Positive remote On/Off implementation

Over-Current Protection

To provide protection in an output over load fault condition, the unit is equipped with internal over-current protection. When the over-current protection is triggered, the unit enters hiccup mode. The units operate normally once the fault condition is removed.

Over-Temperature Protection

ND40 converter does not have built-in over-temperature protection. Hence, to ensure proper, reliable operation, sufficient cooling of the power module is needed over the entire temperature range of the module. Please refer page.9 for detail information.

FEATURES DESCRIPTIONS (CON.)

Output Voltage Programming

The output voltage of the ND40 converter can be programmed to any voltage between 0.9Vdc and 5.0Vdc by connecting one resistor (shown as Rtrim in Figure 26) between the TRIM+ and Trim – pins of the module. Without this external resistor, the output voltage of the module is 0.6 Vdc. To calculate the value of the resistor Rtrim for a particular output voltage Vout, please use the following equation:

$$Rs(\Omega) = \frac{1200}{Vout - 0.6}$$

Rtrim is the external resistor in Ω Vout is the desired output voltage



Figure 26: Circuit configuration for programming output voltage using an external resistor

Table 1 provides Rtrim values required for some common output voltages. By using a trim resistor with 0.1% tolerance and TCR of ± 25 ppm, set point tolerance of $\pm 1\%$ can be achieved as specified in the electrical specification.

Table 1

Vout (V)	Rtrim (Ω)
0.9	4K
1.0	ЗK
1.2	2K
1.5	1.333K
1.8	1K
2.5	631.579
3.3	444.444
5.0	272.727

Voltage Margining

Output voltage margining can be implemented in the ND40 converter by connecting a resistor, R margin-up, between Trim+ pin and Trim- pin for margining-up the output voltage, and by connecting a resistor, R_{margin-down}, between the Trim+ pin and the output pin for margining-down. Figure 27 shows the circuit configuration for output voltage margining. If unused, leave the trim pin unconnected. A calculation tool is available from the evaluation procedure which computes the values of Rmargin-up and Rmargin-down for a specific output voltage and margin percentage.



Figure 27: Circuit configuration for output voltage margining

Test Setup of Output Ripple and Noise, and Start-up Transient

The measurement set-up outlined in Figure 28 has been used for output voltage ripple and noise measurement on NE40 series converters.



Note: Use a 10μ F tantalum and 1μ F capacitor. Scope measurement should be taken by using a BNC connector. Co,min= 300μ F ceramic capacitors

Figure 28: output ripple and noise, start-up transient test setup



THERMAL CONSIDERATION

Thermal management is an important part of the system design. To ensure proper, reliable operation, sufficient cooling of the power module is needed over the entire temperature range of the module. Convection cooling is usually the dominant mode of heat transfer.

Hence, the choice of equipment to characterize the thermal performance of the power module is a wind tunnel.

Thermal Testing Setup

Delta's DC/DC power modules are characterized in heated vertical wind tunnels that simulate the thermal environments encountered in most electronics equipment. This type of equipment commonly uses vertically mounted circuit cards in cabinet racks in which the power modules are mounted.

The following figure shows the wind tunnel characterization setup. The power module is mounted on a test PWB and is vertically positioned within the wind tunnel. The space between the neighboring PWB and the top of the power module is constantly kept at 6.35mm (0.25").

Thermal Derating

Heat can be removed by increasing airflow over the module. To enhance system reliability, the power module should always be operated below the maximum operating temperature. If the temperature exceeds the maximum module temperature, reliability of the unit may be affected.



Note: Wind tunnel test setup figure dimensions are in millimeters and (Inches)

Figure 29: Wind tunnel test setup

THERMAL CURVES (ND12S0A0V40)



Figure 30: Temperature measurement location* The allowed maximum hot spot temperature is defined at 120 $\ensuremath{\mathcal{C}}$



Figure 31: Output current vs. ambient temperature and air velocity @Vin=12V, Vout=5.0V (Worse Orientation)



Figure 32: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=3.3V (Worse Orientation)





Figure 33: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=2.5V (Worse Orientation)



Figure 34: Output current vs. ambient temperature and air velocity @Vin=12V, Vout=1.8V (Worse Orientation)



Figure 35: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=1.5V (Worse Orientation)

NE12S0A0V40PNFC Output Current vs. Ambient Temperature and Air Velocity @ Vin =12V, Vout =1.2V (worse orientation)



Figure 36: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=1.2V (Worse Orientation)



Figure 37: Output current vs. ambient temperature and air velocity @Vin=12V, Vout=0.9V (Worse Orientation)



THERMAL CURVES (ND12S0A0H40)



Figure 38: Temperature measurement location* The allowed maximum hot spot temperature is defined at 110 $^{\circ}$



Figure 39: Output current vs. ambient temperature and air velocity @Vin=12V, Vout=5.0V (Worse Orientation)



Figure 40: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=3.3V (Worse Orientation)



Figure 41: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=2.5V (Worse Orientation)



Figure 42: Output current vs. ambient temperature and air velocity @Vin=12V, Vout=1.8V (Worse Orientation)



Figure 43: Output current vs. ambient temperature and air velocity @ Vin=12V, Vout=1.5V (Worse Orientation)





THERMAL CURVES (ND12S0A0H40)







Figure 45: Output current vs. ambient temperature and air velocity @Vin=12V, Vout=0.9V (Worse Orientation)







SIDE VIEW



PIN#	Function	PIN#	Function
1	Vout	9	PG
2	Vout	10	SENSE-
3	Vout	11	SENSE+
4	GND	12	Vin
5	GND	13	Vin
6	ENABLE	14	GND
7	TRIM-	15	GND
8	TRIM+		

RECOMMENDED P.W.B LAYOUT

NOTES: DIMENSIONS ARE IN MILLIMETERS AND (INCHS) TOLERANCE: X.X mm±0.5 mm(X.XX in.±0.02 in.) X.XX mm±0.25 mm(X.XXX in.±0.010 in.)

MECHANICAL DRAWING (HORIZONTAL)



PIN# PIN# Function Function Vout 10 SENSE-1 2 Vout 11 SENSE+ 3 Vout 12 Vin 13 GND Vin 4 5 14 GND GND 15 GND 6 ENABLE 7 TRIM-16 NC 17 8 TRIM+ NC 9 PG

NOTES: DIMENSIONS ARE IN MILLIMETERS AND (INCHS) TOLERANCE: X.X mm±0.5 mm(X.XX in.±0.02 in.) X.XX mm±0.25 mm(X.XXX in.±0.010 in.) 175'

29.85(1.

15



PART NUMBERING SYSTEM

ND	12	S	0A0	V	40	Р	K	F	Α
Product Series	Input Voltage	Number of outputs	Output Voltage	Mounting	Output Current	ON/OFF Logic	Pin Length		Option Code
ND - Non-isolated Series	12 - 8.0~13.8V	S - Single Output	0A0 - Programmable	V - Vertical H - Horizontal	40 - 40A	P- Positive	K – 0.110" N - 0.145"	F- RoHS 6/6 (Lead Free) Space- RoHS5/6	A- Standard Function D- pin length: 0.165"

MODEL LIST

Model Name	Packaging	Input Voltage	Output Voltage	Output Current	Efficiency 12Vin @ 5Vo Full load
ND12S0A0V40PKFA	Vertical	8.0V ~ 13.8Vdc	0.9V ~ 5.0V	40A	94%
ND12S0A0H40PNFA	Horizontal	8.0V ~ 13.8Vdc	0.9V ~ 5.0V	40A	94%

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WARRANTY

Delta offers a two (2) year limited warranty. Complete warranty information is listed on our web site or is available upon request from Delta.

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